Likelihood calculations for *vsn*

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Contents

1 Introduction

This vignette contains the computations that underlie the numerical code of *vsn*. If you are a new user and looking for an introduction on how to **use** *vsn*, please refer to the vignette *Robust calibration and variance stabilization with vsn*, which is provided separately.

2 Setup and Notation

Consider the model

$$\text{arsinh}\,(f(b_i) \cdot y_{ki} + a_i) = \mu_k + \varepsilon_{ki} \tag{1}$$

where μ_k, for $k = 1, \ldots, n$, and a_i, b_i, for $i = 1, \ldots, d$ are real-valued parameters, f is a function $\mathbb{R} \to \mathbb{R}$ (see below), and ε_{ki} are i.i.d. Normal with mean 0 and variance σ^2. y_{ki} are the data. In applications to μarray data, k indexes the features and i the arrays and/or colour channels.

Examples for f are $f(b) = b$ and $f(b) = e^b$. The former is the most obvious choice; in that case we will usually need to require $b_i > 0$. The choice $f(b) = e^b$ assures that the factor in front of y_{ki} is positive for all $b \in \mathbb{R}$, and as it turns out, simplifies some of the computations.

In the following calculations, I will also use the notation

$$
\begin{aligned}
Y \equiv Y(y, a, b) &= f(b) \cdot y + a \\
h \equiv h(y, a, b) &= \operatorname{arsinh}(f(b) \cdot y + a).
\end{aligned}
$$

(2)

(3)

The probability of the data $(y_{ki})_{k=1...n,\ i=1...d}$ lying in a certain volume element of y-space (hyperrectangle with sides $[y_{ki}^\alpha, y_{ki}^\beta]$) is

$$
P = \prod_{k=1}^{n} \prod_{i=1}^{d} \int_{y_{ki}^\alpha}^{y_{ki}^\beta} dy_{ki} \ p_{\mathrm{Normal}}(h(y_{ki}), \mu_k, \sigma^2) \ \frac{dh}{dy}(y_{ki}),
$$

(4)

where μ_k is the expectation value for feature k and σ^2 the variance.

With

$$
p_{\mathrm{Normal}}(x, \mu, \sigma^2) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{(x - \mu)^2}{2\sigma^2}\right)
$$

(5)

the likelihood is

$$
L = \left(\frac{1}{\sqrt{2\pi\sigma^2}}\right)^{nd} \prod_{k=1}^{n} \prod_{i=1}^{d} \exp\left(-\frac{(h(y_{ki}) - \mu_k)^2}{2\sigma^2}\right) \cdot \frac{dh}{dy}(y_{ki}).
$$

(6)

For the following, I will need the derivatives

$$
\begin{aligned}
\frac{\partial Y}{\partial a} &= 1 \\
\frac{\partial Y}{\partial b} &= y \cdot f'(b) \\
\frac{dh}{dy} &= \frac{f(b)}{\sqrt{1 + (f(b)y + a)^2}} = \frac{f(b)}{\sqrt{1 + Y^2}}, \\
\frac{\partial h}{\partial a} &= \frac{1}{\sqrt{1 + Y^2}}, \\
\frac{\partial h}{\partial b} &= \frac{y}{\sqrt{1 + Y^2}} \cdot f'(b).
\end{aligned}
$$

(7)

(8)

(9)

(10)

(11)

Note that for $f(b) = b$, we have $f'(b) = 1$, and for $f(b) = e^b$, $f'(b) = f(b) = e^b$.

3 Likelihood for Incremental Normalization

Here, *incremental normalization* means that the model parameters $\mu_1, \ldots, \mu_n$ and σ^2 are already known from a fit to a previous set of μarrays, i.e. a set of reference arrays. See Section 4 for the profile likelihood approach that is used if $\mu_1, \ldots, \mu_n$ and σ^2 are not

known and need to be estimated from the same data. Versions ≥ 2.0 of the *vsn* package implement both of these approaches; in versions 1.X only the profile likelihood approach was implemented, and it was described in the initial publication [1].

First, let us note that the likelihood (6) is simply a product of independent terms for different i. We can optimize the parameters (a_i, b_i) separately for each $i = 1, \ldots, d$. From the likelihood (6) we get the i-th negative log-likelihood

$$-\log(L) = \sum_{i=1}^{d} -LL_i \tag{12}$$

$$-LL_i = \frac{n}{2} \log\left(2\pi\sigma^2\right) + \sum_{k=1}^{n} \left(\frac{(h(y_{ki}) - \mu_k)^2}{2\sigma^2} + \log \frac{\sqrt{1 + Y_{ki}^2}}{f(b_i)} \right) \tag{13}$$

$$= \frac{n}{2} \log\left(2\pi\sigma^2\right) - n \log f(b_i) + \sum_{k=1}^{n} \left(\frac{(h(y_{ki}) - \mu_k)^2}{2\sigma^2} + \frac{1}{2} \log\left(1 + Y_{ki}^2\right) \right) \tag{14}$$

This is what we want to optimize as a function of a_i and b_i. The optimizer benefits from the derivatives. The derivative with respect to a_i is

$$\frac{\partial}{\partial a_i}(-LL_i) = \sum_{k=1}^{n} \left(\frac{h(y_{ki}) - \mu_k}{\sigma^2} + \frac{Y_{ki}}{\sqrt{1 + Y_{ki}^2}} \right) \cdot \frac{1}{\sqrt{1 + Y_{ki}^2}}$$

$$= \sum_{k=1}^{n} \left(\frac{r_{ki}}{\sigma^2} + A_{ki} Y_{ki} \right) A_{ki} \tag{15}$$

and with respect to b_i

$$\frac{\partial}{\partial b_i}(-LL_i) = -n \frac{f'(b_i)}{f(b_i)} + \sum_{k=1}^{n} \left(\frac{h(y_{ki}) - \mu_k}{\sigma^2} + \frac{Y_{ki}}{\sqrt{1 + Y_{ki}^2}} \right) \cdot \frac{y_{ki}}{\sqrt{1 + Y_{ki}^2}} \cdot f'(b_i)$$

$$= -n \frac{f'(b_i)}{f(b_i)} + f'(b_i) \sum_{k=1}^{n} \left(\frac{r_{ki}}{\sigma^2} + A_{ki} Y_{ki} \right) A_{ki} y_{ki} \tag{16}$$

Here, I have introduced the following shorthand notation for the "intermediate results" terms

$$r_{ki} = h(y_{ki}) - \mu_k \tag{17}$$

$$A_{ki} = \frac{1}{\sqrt{1 + Y_{ki}^2}}. \tag{18}$$

Variables for these intermediate values are also used in the C code to organise the computations of the gradient.

3

4 Profile Likelihood

If $\mu_1, \ldots, \mu_n$ and σ^2 are not already known, we can plug in their maximum likelihood estimates, obtained from optimizing LL for $\mu_1, \ldots, \mu_n$ and σ^2:

$$\hat{\mu}_k = \frac{1}{d} \sum_{j=1}^{d} h(y_{kj}) \tag{19}$$

$$\hat{\sigma}^2 = \frac{1}{nd} \sum_{k=1}^{n} \sum_{j=1}^{d} (h(y_{kj}) - \hat{\mu}_k)^2 \tag{20}$$

into the negative log-likelihood. The result is called the negative profile log-likelihood

$$-PLL = \frac{nd}{2} \log \left(2\pi\hat{\sigma}^2\right) + \frac{nd}{2} - n \sum_{j=1}^{d} \log f(b_j) + \frac{1}{2} \sum_{k=1}^{n} \sum_{j=1}^{d} \log \sqrt{1 + Y_{kj}^2}. \tag{21}$$

Note that this no longer decomposes into a sum of terms for each j that are independent of each other – the terms for different j are coupled through Equations (19) and (20). We need the following derivatives.

$$\frac{\partial \hat{\sigma}^2}{\partial a_i} = \frac{2}{nd} \sum_{k=1}^{n} r_{ki} \frac{\partial h(y_{ki})}{\partial a_i}$$

$$= \frac{2}{nd} \sum_{k=1}^{n} r_{ki} A_{ki} \tag{22}$$

$$\frac{\partial \hat{\sigma}^2}{\partial b_i} = \frac{2}{nd} \cdot f'(b_i) \sum_{k=1}^{n} r_{ki} A_{ki} y_{ki} \tag{23}$$

So, finally

$$\frac{\partial}{\partial a_i}(-PLL) = \frac{nd}{2\hat{\sigma}^2} \cdot \frac{\partial \hat{\sigma}^2}{\partial a_i} + \sum_{k=1}^{n} A_{ki}^2 Y_{ki}$$

$$= \sum_{k=1}^{n} \left(\frac{r_{ki}}{\hat{\sigma}^2} + A_{ki} Y_{ki}\right) A_{ki} \tag{24}$$

$$\frac{\partial}{\partial b_i}(-PLL) = -n \frac{f'(b_i)}{f(b_i)} + f'(b_i) \sum_{k=1}^{n} \left(\frac{r_{ki}}{\hat{\sigma}^2} + A_{ki} Y_{ki}\right) A_{ki} y_{ki} \tag{25}$$

5 Summary

Likelihoods, from Equations (12) and (21):

$$-LL_i = \underbrace{\frac{n}{2}\log\left(2\pi\sigma^2\right)}_{\text{scale}} + \underbrace{\sum_{k=1}^{n}\frac{(h(y_{ki})-\mu_k)^2}{2\sigma^2}}_{\text{residuals}} \underbrace{-n\log f(b_i) + \frac{1}{2}\sum_{k=1}^{n}\log(1+Y_{ki}^2)}_{\text{jacobian}} \quad (26)$$

$$-PLL = \underbrace{\frac{nd}{2}\log\left(2\pi\hat{\sigma}^2\right)}_{\text{scale}} + \underbrace{\frac{nd}{2}}_{\text{residuals}} + \underbrace{\sum_{i=1}^{d}\left(-n\log f(b_i) + \frac{1}{2}\sum_{k=1}^{n}\log(1+Y_{ki}^2)\right)}_{\text{jacobian}} \quad (27)$$

The computations in the C code are organised into steps for computing the terms "scale", "residuals" and "jacobian".

Partial derivatives with respect to a_i, from Equations (15) and (24):

$$\frac{\partial}{\partial a_i}(-LL_i) = \sum_{k=1}^{n}\left(\frac{r_{ki}}{\sigma^2} + A_{ki}Y_{ki}\right)A_{ki} \quad (28)$$

$$\frac{\partial}{\partial a_i}(-PLL) = \sum_{k=1}^{n}\left(\frac{r_{ki}}{\hat{\sigma}^2} + A_{ki}Y_{ki}\right)A_{ki} \quad (29)$$

Partial derivatives with respect to b_i, from Equations (16) and (25):

$$\frac{\partial}{\partial b_i}(-LL_i) = -n\frac{f'(b_i)}{f(b_i)} + f'(b_i)\sum_{k=1}^{n}\left(\frac{r_{ki}}{\sigma^2} + A_{ki}Y_{ki}\right)A_{ki}y_{ki} \quad (30)$$

$$\frac{\partial}{\partial b_i}(-PLL) = -n\frac{f'(b_i)}{f(b_i)} + f'(b_i)\sum_{k=1}^{n}\left(\frac{r_{ki}}{\hat{\sigma}^2} + A_{ki}Y_{ki}\right)A_{ki}y_{ki}. \quad (31)$$

Note that the terms have many similarities – this is used in the implementation in the C code.

References

[1] W. Huber, A. von Heydebreck, H. Sültmann, A. Poustka, and M. Vingron. Variance stablization applied to microarray data calibration and to quantification of differential expression. *Bioinformatics*, 18:S96–S104, 2002. 2

[2] W. Huber, A. von Heydebreck, H. Sültmann, A. Poustka, and M. Vingron. Parameter estimation for the calibration and variance stabilization of microarray data. *Statistical Applications in Genetics and Molecular Biology*, Vol. 2: No. 1, Article 3, 2003. http://www.bepress.com/sagmb/vol2/iss1/art3